

Miroslav Krstić and Hua Deng

Stabilization of Nonlinear Uncertain Systems



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Stabilization Of Nonlinear Uncertain Systems:

Stabilization of Nonlinear Uncertain Systems Miroslav Krstić,1998

Stabilization of Nonlinear Uncertain Systems

Miroslav Krstic,Hua Deng,1998-05-21 This monograph presents the fundamentals of global stabilization and optimal control of nonlinear systems with uncertain models It offers a unified view of deterministic disturbance attenuation stochastic control and adaptive control for nonlinear systems The book addresses researchers in the areas of robust and adaptive nonlinear control nonlinear H infinity stochastic control and other related areas of control and dynamical systems theory **New**

Results on Practical Stability for Linear and Nonlinear Uncertain Systems Laura Celentano,2012

System Theory

Theodore E. Djaferis,Irvin C. Schick,2012-12-06 System Theory Modeling Analysis and Control contains thirty three scientific papers covering a wide range of topics in systems and control These papers have been contributed to a symposium organized to celebrate Sanjoy K Mitter s 65th birthday The following research topics are addressed distributed parameter systems stochastic control filtering and estimation optimization and optimal control image processing and vision hierarchical systems and hybrid control nonlinear systems and linear systems Also included are three survey papers on optimization nonlinear filtering and nonlinear systems Recent advances are reported on the behavioral approach to systems the relationship between differential games and robust control estimation of diffusion processes Markov processes optimal control hybrid control stochastic control spectral estimation nonconvex quadratic programming robust control control algorithms and quantized linear systems Innovative explorations are carried out on quantum systems from a control theory perspective option valuation and hedging three dimensional medical visualization computational structure biology image processing and hierarchical approaches to complex systems flow control scheduling and force feedback in fluid mechanics The contents reflect on past research accomplishments current research activity and future research directions in systems and control theory **Model-Free Stabilization by Extremum Seeking** Alexander Scheinker,Miroslav Krstić,2016-12-23

With this brief the authors present algorithms for model free stabilization of unstable dynamic systems An extremum seeking algorithm assigns the role of a cost function to the dynamic system s control Lyapunov function clf aiming at its minimization The minimization of the clf drives the clf to zero and achieves asymptotic stabilization This approach does not rely on or require knowledge of the system model Instead it employs periodic perturbation signals along with the clf The same effect is achieved as by using clf based feedback laws that profit from modeling knowledge but in a time average sense Rather than use integrals of the systems vector field we employ Lie bracket based i e derivative based averaging The brief contains numerous examples and applications including examples with unknown control directions and experiments with charged particle accelerators It is intended for theoretical control engineers and mathematicians and practitioners working in various industrial areas and in robotics Stochastic Nonlinear Stabilization Hua Deng,2001

Robust Control of Nonlinear Uncertain Systems Zhihua Qu,1998-04-29 This timely work presents the definitive treatment of stability analysis and robust

control design for nonlinear uncertain systems While other books on the subject deal with robust control in linear systems this is the first book to tackle robust control design for such nonlinear entities as power systems robotics and more It combines examples proofs and applications clearly showing how to build high performance and better control into systems that are too complex to be modeled accurately A unique feature of this book is its Lyapunov based approach to control design which is the only universal approach for nonlinear systems The Lyapunov direct method is used here to develop all design procedures to correlate leading techniques in the field to the structural properties of uncertain systems and to compare robust and nonrobust types of controls such as adaptive control learning control and optimal control The subject is introduced with a self contained treatment of the nonlinear stability theory originally proposed by Lyapunov and LaSalle Emphasizing the basics the introductory chapters incorporate three types of solutions stability concepts and various theorems The main body of the text offers a comprehensive treatment for current design methods including state space robust control designs properties of various robust controllers input output control and discrete robust control designs In Robust Control of Nonlinear Uncertain Systems author Zhihua Qu presents the complete set of control design procedures for nonlinear uncertain systems including backward recursive design forward recursive design recursive interlacing design feedback linearization nonlinear optimal control and sub optimal control Also featured here is the breakthrough recursive interlacing design that facilitates robust control for uncertain systems with all cascaded feedback and feedforward dynamics Throughout Professor Qu presents the pros and cons of specific methods rationales for choosing particular design parameters and tips on questions of stability performance and systems structure For engineers and graduate students in mechanical electrical and aerospace engineering Robust Control of Nonlinear Uncertain Systems imparts the technical know how for effective design explores key theoretical issues in control and provides insight into future trends in the field

Robust Control Design Using H_∞ Methods Ian R. Petersen, Valery A. Ugrinovskii, Andrey V. Savkin, 2012-12-06 This is a unified collection of important recent results for the design of robust controllers for uncertain systems primarily based on H_2 control theory or its stochastic counterpart risk sensitive control theory Two practical applications are used to illustrate the methods throughout Deterministic Control of Nonlinear Uncertain Systems Sandeep Pandey, 1992 Extremum Seeking Through Delays and PDEs Tiago Roux Oliveira, Miroslav Krstic, 2022-12-05 Extremum Seeking through Delays and PDEs the first book on the topic expands the scope of applicability of the extremum seeking method from static and finite dimensional systems to infinite dimensional systems Readers will find numerous algorithms for model free real time optimization are developed and their convergence guaranteed extensions from single player optimization to noncooperative games under delays and PDEs are provided the delays and PDEs are compensated in the control designs using the PDE backstepping approach and stability is ensured using infinite dimensional versions of averaging theory and accessible and powerful tools for analysis This book is intended for control engineers in all disciplines electrical mechanical aerospace chemical

mathematicians physicists biologists and economists It is appropriate for graduate students researchers and industrial users
 ,1997 **Robust Adaptive Dynamic Programming** Yu Jiang,Zhong-Ping Jiang,2017-05-08 A comprehensive look at
 state of the art ADP theory and real world applications This book fills a gap in the literature by providing a theoretical
 framework for integrating techniques from adaptive dynamic programming ADP and modern nonlinear control to address
 data driven optimal control design challenges arising from both parametric and dynamic uncertainties Traditional model
 based approaches leave much to be desired when addressing the challenges posed by the ever increasing complexity of real
 world engineering systems An alternative which has received much interest in recent years are biologically inspired
 approaches primarily RADP Despite their growing popularity worldwide until now books on ADP have focused nearly
 exclusively on analysis and design with scant consideration given to how it can be applied to address robustness issues a new
 challenge arising from dynamic uncertainties encountered in common engineering problems Robust Adaptive Dynamic
 Programming zeros in on the practical concerns of engineers The authors develop RADP theory from linear systems to
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 discussions of novel applications for RADP theory including an entire chapter on how it can be used as a computational
 mechanism of human movement control Robust Adaptive Dynamic Programming is both a valuable working resource and an
 intriguing exploration of contemporary ADP theory and applications for practicing engineers and advanced students in
 systems theory control engineering computer science and applied mathematics **SIAM Journal on Control and
 Optimization** Society for Industrial and Applied Mathematics,2007 **Robust Control Design 2000 (ROCOND 2000)**
 Vladimír Kučera,Michael Šebek,2000 This Proceedings contains the papers presented at the IFAC Symposium on Robust
 Control Design held in Prague on 21-23 June 2000 The technical program included 21 sessions on robust control and related
 topics in identification and signal processing The methods presented in these sessions included linear matrix inequalities
 polynomial techniques sliding modes optimal control fuzzy and adaptive control Attention was also paid to linear as well as
 nonlinear systems The highlights of the technical program were two plenary lectures by J Geromel Universidade Estadual de
 Campinas Brazil and H Kwakernaak University of Twente The Netherlands **Proceedings of the 33rd IEEE Conference
 on Decision and Control** ,1994 **Reinforcement Learning for Optimal Feedback Control** Rushikesh
 Kamalapurkar,Patrick Walters,Joel Rosenfeld,Warren Dixon,2018-05-10 Reinforcement Learning for Optimal Feedback

Control develops model based and data driven reinforcement learning methods for solving optimal control problems in nonlinear deterministic dynamical systems In order to achieve learning under uncertainty data driven methods for identifying system models in real time are also developed The book illustrates the advantages gained from the use of a model and the use of previous experience in the form of recorded data through simulations and experiments The book s focus on deterministic systems allows for an in depth Lyapunov based analysis of the performance of the methods described during the learning phase and during execution To yield an approximate optimal controller the authors focus on theories and methods that fall under the umbrella of actor critic methods for machine learning They concentrate on establishing stability during the learning phase and the execution phase and adaptive model based and data driven reinforcement learning to assist readers in the learning process which typically relies on instantaneous input output measurements This monograph provides academic researchers with backgrounds in diverse disciplines from aerospace engineering to computer science who are interested in optimal reinforcement learning functional analysis and functional approximation theory with a good introduction to the use of model based methods The thorough treatment of an advanced treatment to control will also interest practitioners working in the chemical process and power supply industry

Robust Control Via Variable Structure and Lyapunov Techniques Franco Garofalo, Luigi Glielmo, 1996 A large part of today s fervour on robust control research is focused on those techniques which utilise the Variable Structure Control Method and Lyapunov s Second Method and which constitute the backbone of the so called deterministic control of uncertain systems The chapters of this book cover a large spectrum of the recent research and introduce the most innovative ideas in the field Contained within the volume the reader will find a survey of control Lyapunov functions new structures of sliding mode controllers with discussion on higher order sliding modes new techniques for the design of direct and indirect adaptive controllers an introduction to the geometric theory of flat systems controllers for plants with component wise bounded inputs robust design via linear matrix inequalities and polytopic covering and some issues on the dissipativity and absolute stability of nonli near systems

Journal of Dynamic Systems, Measurement, and Control ,2004 Publishes theoretical and applied original papers in dynamic systems Theoretical papers present new theoretical developments and knowledge for controls of dynamical systems together with clear engineering motivation for the new theory Applied papers include modeling simulation and corroboration of theory with emphasis on demonstrated practicality

Proceedings of the 26th IEEE Conference on Decision and Control ,1987

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