Pedro Albertos
and Antonio Sala (Eds.)

Iterative
Identification
and Control

Springer

Iterative Identification And Control Advances In Theory And Applications

Huangqi Zhang

Iterative Identification And Control Advances In Theory And Applications:

    Iterative Identification and Control P. Albertos Pérez,Doctor Antonio Sala,2002-05-21 An exposition of the interplay between the modelling of dynamic systems and the design of feedback controllers based on these models The authors of individual chapters are some of the most renowned and authoritative figures in the fields of system identification and control design   **Mathematical Reviews** ,2004   **European Control Conference 1995** ,1995-09-05 Proceedings of the European Control Conference 1995 Rome Italy 5 8 September 1995   Mechatronics and Robotics Marina Indri,Roberto Oboe,2020-11-24 The term mechatronics was coined in 1969 merging mecha from mechanism and tronics from electronics to reflect the original idea at the basis of this discipline that is the integration of electrical and mechanical systems into a single device The spread of this term and of mechatronics itself has been growing in the years including new aspects and disciplines like control engineering computer engineering and communication information engineering Nowadays mechatronics has a well defined and fundamental role in strict relation with robotics Drawing a sharp border between mechatronics and robotics is impossible as they share many technologies and objectives Advanced robots could be defined as mechatronic devices equipped with a smart brain but there are also up to date mechatronic devices used in tight interaction with humans that are governed by smart architectures for example for safety purposes Aim of this book is to offer a wide overview of new research trends and challenges for both mechatronics and robotics through the contribution of researchers from different institutions providing their view on specific subjects they consider as hot topics in both fields with attention to new fields of application new challenges to the research communities and new technologies available The reader of this book will enjoy the various contributions as they have been prepared with actual applications in mind along a journey from advanced actuators and sensors to human robot interaction through robot control navigation planning and programming issues The book presents several state of the art solutions like multiple stage actuation to cope with conflicting specification of large motion spans ultra high accuracy model based control for high tech mechatronic systems modern approaches of software systems engineering to robotics aand humanoids for human assistance The reader can also find new techniques in approaching the design of mechatronic systems in some possible industrial and service robotics scenarios with a particular attention for the interaction between humans and mechanisms   American Book Publishing Record ,2002   Two-Degree-of-Freedom Control Systems László Kevickzy,Cs. Banyasz,2015-06-18 This book covers the most important issues from classical and robust control deterministic and stochastic control system identification and adaptive and iterative control strategies It covers most of the known control system methodologies using a new base the Youla parameterization YP This concept is introduced and extended for TDOF control loops The Keviczky Banyasz parameterization KP method developed for closed loop systems is also presented The book is valuable for those who want to see through the jungle of available methods by using a unified approach and for those who want to prepare computer code with a given algorithm Provides comprehensive

coverage of the most widely used control system methodologies The first book to use the Youla parameterization YP as a common base for comparison and algorithm development Compares YP and Keviczky Banyasz KB parameterization to help you write your own computer algorithms **AIChE Symposium Series** American Institute of Chemical Engineers,1971

Advanced Model Predictive Control Tao Zheng,2011-07-05 Model Predictive Control MPC refers to a class of control algorithms in which a dynamic process model is used to predict and optimize process performance From lower request of modeling accuracy and robustness to complicated process plants MPC has been widely accepted in many practical fields As the guide for researchers and engineers all over the world concerned with the latest developments of MPC the purpose of Advanced Model Predictive Control is to show the readers the recent achievements in this area The first part of this exciting book will help you comprehend the frontiers in theoretical research of MPC such as Fast MPC Nonlinear MPC Distributed MPC Multi Dimensional MPC and Fuzzy Neural MPC In the second part several excellent applications of MPC in modern industry are proposed and efficient commercial software for MPC is introduced Because of its special industrial origin we believe that MPC will remain energetic in the future **Journal of Dynamic Systems, Measurement, and Control** ,1996 Publishes theoretical and applied original papers in dynamic systems Theoretical papers present new theoretical developments and knowledge for controls of dynamical systems together with clear engineering motivation for the new theory Applied papers include modeling simulation and corroboration of theory with emphasis on demonstrated practicality

Chemical Process Control-VI James Blake Rawlings,Babatunde Ayodeji Ogunnaike,John W. Eaton,2002 Electronic version of the proceedings and papers of the conference along with an ISO9660 file system with Rock Ridge attributes

The British National Bibliography Arthur James Wells,2002 Chemical Process Control-VI American Institute of Chemical Engineers,2002 1995 American Control Conference American Automatic Control Council,1995 *Chemical Abstracts* ,2002 **Proceedings of the 2000 IEEE International Symposium on Intelligent Control** ,2000 *2005 IEEE International Symposium on Intelligent Control & 13th Mediterranean Conference on Control and Automation* ,2005 **Proceedings of the 33rd IEEE Conference on Decision and Control** ,1994 **Forthcoming Books** Rose Arny,2002 **Astrodynamics** ,2006 **Blind Image Deconvolution** Subhasis Chaudhuri,Rajbabu Velmurugan,Renu Rameshan,2014-09-22 Blind deconvolution is a classical image processing problem which has been investigated by a large number of researchers over the last four decades The purpose of this monograph is not to propose yet another method for blind image restoration Rather the basic issue of deconvolvability has been explored from a theoretical view point Some authors claim very good results while quite a few claim that blind restoration does not work The authors clearly detail when such methods are expected to work and when they will not In order to avoid the assumptions needed for convergence analysis in the Fourier domain the authors use a general method of convergence analysis used for alternate minimization based on three point and four point properties of the points in the image space The authors prove that all points in the image

space satisfy the three point property and also derive the conditions under which four point property is satisfied This provides the conditions under which alternate minimization for blind deconvolution converges with a quadratic prior Since the convergence properties depend on the chosen priors one should design priors that avoid trivial solutions Hence a sparsity based solution is also provided for blind deconvolution by using image priors having a cost that increases with the amount of blur which is another way to prevent trivial solutions in joint estimation This book will be a highly useful resource to the researchers and academicians in the specific area of blind deconvolution

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